

#### Testing of Thermal Interface Materials: Preliminary Observations

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- Purpose of thermal interface materials:
  - enhance heat transfer at joint by reducing thermal contact resistance
  - provide better thermal contact between chip (source) and heat sink / spreader (sink)
- Applications:
  - heat sink attach
  - heat spreader attach
- Widely used in industry





- Interface materials are divided into four categories:
  - greases and liquids
  - compliant materials: deform more than 10% under clamping force
  - hard rubber materials: deform less than 10% under clamping force
  - thermally conductive materials: materials such as ceramics and plastics that require high clamping force





- Design and construct apparatus for thermal testing of interface materials
- Measure joint resistance and thermal conductivity as function of
  - temperature
  - contact pressure
  - material properties
  - surface characteristics

### **Measurement Procedure**



- Joint resistance and conductivity calculated based on temperature and thickness measurements
- Thermal joint resistance

$$R_{\text{joint}} = \frac{\Delta T_{\text{joint}}}{Q} \qquad \qquad \Delta T_{\text{joint}} = \text{ joint temperature drop} \\ Q = \text{ total heat flow rate}$$

Thermal conductivity

$$k = \frac{1}{R_{\text{joint}}} \frac{t_{\text{joint}}}{A_{\text{joint}}} \qquad t_{\text{joint}} = \text{ joint thickness}$$
$$A_{\text{joint}} = \text{ joint cross-sectional area}$$

## Heat Flux Meter





- Isotropic, constant cross section cylinders of known conductivity, k = f(T)
- Dual-purpose device
  - calculate heat flow rate
  - determine joint temperatures

Temperature gradient measured by RTDs

- $\checkmark$  accuracy < 0.1 °C
- equal spacing 10 mm





Heat flow rate:

 $Q = k A \frac{dT}{dx}$ 

 Temperature gradient from linear fit of temperature data

$$\frac{dT}{dx} = m$$



 Total heat flow rate = average of upper and lower flux meters





 Joint temperature determined by extrapolating temperature gradient to the joint surface









- All testing performed in vacuum chamber
   ✓ P ≈ 10 Pa (1×10<sup>-4</sup> atm)
  - remove heat losses due to convection
  - maintain close
    balance between flux
    meters













- Load cell
  - 100 or 1000 lbs
- Spring to compensate for thermal expansion
- Thrust bearing to remove torque loads
- Electric cylinder
  - digitally controlled stepper motor
  - 400 steps / rev 0.1"
    per revolution





# Thickness and Deflection





Signal Processing Card

#### Lasers

- ✓ 5 *mW*
- ✓ 670 nm wavelength
- $\checkmark$  100 µm at 4" columation

#### Detectors