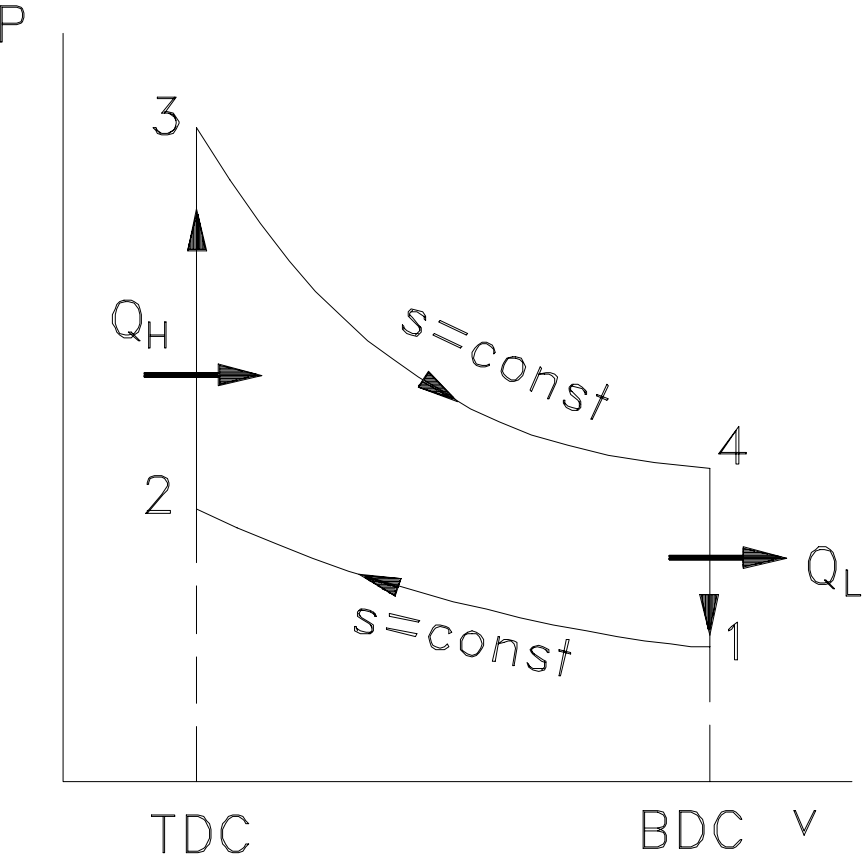
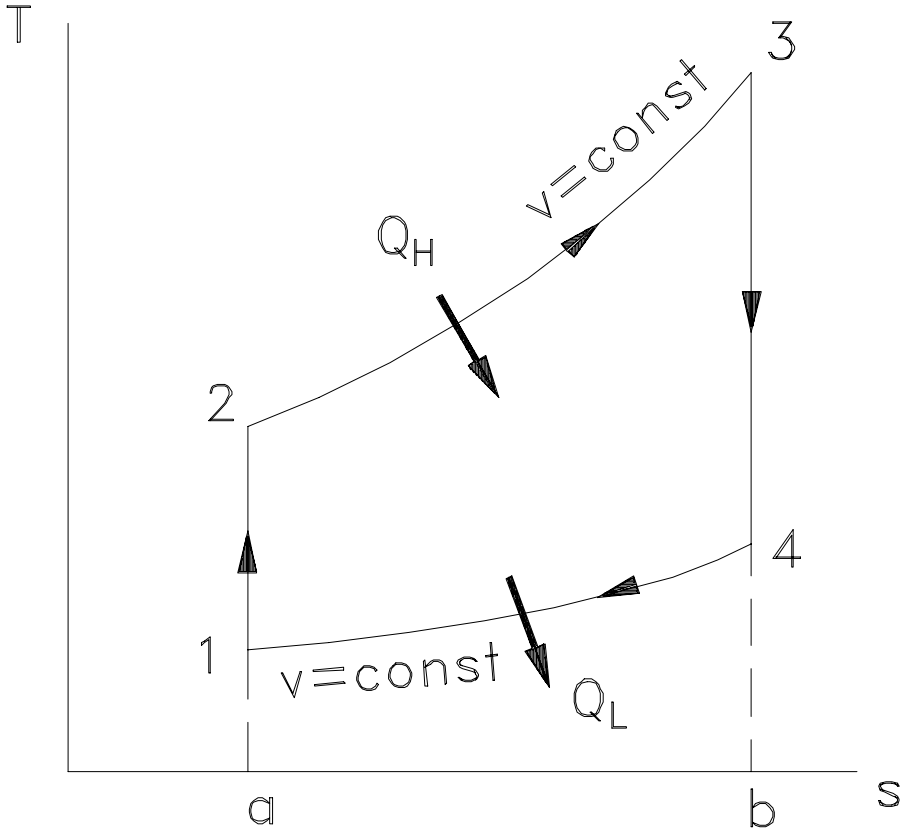

P
3
Q_H
s=const
4
2
Q_L
s=const
1
TDC
BDC
v


T
3
v=const
Q_H
2
4
1
v=const
Q_L
a
b
s